

# NAG C Library Function Document

## nag\_dstebz (f08jjc)

### 1 Purpose

nag\_dstebz (f08jjc) computes some (or all) of the eigenvalues of a real symmetric tridiagonal matrix, by bisection.

### 2 Specification

```
void nag_dstebz (Nag_RangeType range, Nag_EigValRankType rank, Integer n,
  double vl, double vu, Integer il, Integer iu, double abstol, const double d[],
  const double e[], Integer *m, Integer *nsplit, double w[], Integer iblock[],
  Integer isplit[], NagError *fail)
```

### 3 Description

nag\_dstebz (f08jjc) uses bisection to compute some or all of the eigenvalues of a real symmetric tridiagonal matrix  $T$ .

It searches for zero or negligible off-diagonal elements of  $T$  to see if the matrix splits into block diagonal form:

$$T = \begin{pmatrix} T_1 & & & \\ & T_2 & & \\ & & \ddots & \\ & & & T_p \end{pmatrix}.$$

It performs bisection on each of the blocks  $T_i$  and returns the block index of each computed eigenvalue, so that a subsequent call to nag\_dstein (f08jkc) to compute eigenvectors can also take advantage of the block structure.

### 4 References

Kahan W (1966) Accurate eigenvalues of a symmetric tridiagonal matrix *Report CS41* Stanford University

### 5 Parameters

1: **range** – Nag\_RangeType *Input*

*On entry:* indicates which eigenvalues are required as follows:

if **range** = **Nag\_AllValues**, then all the eigenvalues are required;

if **range** = **Nag\_Interval**, then all the eigenvalues in the half-open interval  $(\mathbf{vl}, \mathbf{vu}]$  are required;

if **range** = **Nag\_Indices**, then eigenvalues with indices **il** to **iu** are required.

*Constraint:* **range** = **Nag\_AllValues**, **Nag\_Interval** or **Nag\_Indices**.

2: **rank** – Nag\_EigValRankType *Input*

*On entry:* indicates the order in which the eigenvalues and their block numbers are to be stored as follows:

if **rank** = **Nag\_ByBlock**, then the eigenvalues are to be grouped by split-off block and ordered from smallest to largest within each block;

if **rank** = **Nag\_Entire**, then the eigenvalues for the entire matrix are to be ordered from smallest to largest.

*Constraint:* **rank** = **Nag\_ByBlock** or **Nag\_Entire**.

3: **n** – Integer *Input*

*On entry:* *n*, the order of the matrix *T*.

*Constraint:*  $n \geq 0$ .

4: **vl** – double *Input*

5: **vu** – double *Input*

*On entry:* if **range** = **Nag\_Interval**, the lower and upper bounds, respectively, of the half-open interval **(vl,vu]** within which the required eigenvalues lie.

Not referenced if **range** = **Nag\_AllValues** or **Nag\_Indices**.

*Constraint:*

if **range** = **Nag\_Interval**,  $vl < vu$ .

6: **il** – Integer *Input*

7: **iu** – Integer *Input*

*On entry:* if **range** = **Nag\_Indices**, the indices of the first and last eigenvalues, respectively, to be computed (assuming that the eigenvalues are in ascending order).

Not referenced if **range** = **Nag\_AllValues** or **Nag\_Interval**.

*Constraint:*

if **range** = **Nag\_Indices**,  $1 \leq il \leq iu \leq n$ .

8: **abstol** – double *Input*

*On entry:* the absolute tolerance to which each eigenvalue is required. An eigenvalue (or cluster) is considered to have converged if it lies in an interval of width  $\leq \mathbf{abstol}$ . If  $\mathbf{abstol} \leq 0.0$ , then the tolerance is taken as *machine precision*  $\times \|T\|_1$ .

9: **d[dim]** – const double *Input*

**Note:** the dimension, *dim*, of the array **d** must be at least  $\max(1, n)$ .

*On entry:* the diagonal elements of the tridiagonal matrix *T*.

10: **e[dim]** – const double *Input*

**Note:** the dimension, *dim*, of the array **e** must be at least  $\max(1, n - 1)$ .

*On entry:* the off-diagonal elements of the tridiagonal matrix *T*.

11: **m** – Integer \* *Output*

*On exit:* *m*, the actual number of eigenvalues found.

12: **nsplit** – Integer \* *Output*

*On exit:* the number of diagonal blocks which constitute the tridiagonal matrix *T*.

13: **w[dim]** – double *Output*

**Note:** the dimension, *dim*, of the array **w** must be at least  $\max(1, n)$ .

*On exit:* the required eigenvalues of the tridiagonal matrix *T* stored in **w[0]** to **w[m]**.

14: **iblock**[*dim*] – Integer

Output

**Note:** the dimension, *dim*, of the array **iblock** must be at least  $\max(1, \mathbf{n})$ .

*On exit:* at each row/column *j* where  $\mathbf{e}[j]$  is zero or negligible, *T* is considered to split into a block diagonal matrix and **iblock**[*i*] contains the block number of the eigenvalue stored in **w**[*i*], for  $i = 1, 2, \dots, m$ . Note that **iblock**[*i*] < 0 for some *i* whenever **fail** = 1 or 3 (see Section 6) and **range** = **Nag\_AllValues** or **Nag\_Interval**.

15: **isplit**[*dim*] – Integer

Output

**Note:** the dimension, *dim*, of the array **isplit** must be at least  $\max(1, \mathbf{n})$ .

*On exit:* the leading **nsplit** elements contain the points at which *T* splits up into sub-matrices as follows. The first sub-matrix consists of rows/columns 1 to **isplit**[0], the second sub-matrix consists of rows/columns **isplit**[0] + 1 to **isplit**[1], ..., and the **nsplit**(th) sub-matrix consists of rows/columns **isplit**[**nsplit** - 2] + 1 to **isplit**[**nsplit** - 1] (= *n*).

16: **fail** – NagError \*

Output

The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **n** = *<value>*.

Constraint: **n** ≥ 0.

### NE\_ENUM\_INT\_3

On entry, **range** = *<value>*, **n** = *<value>*, **il** = *<value>*, **iu** = *<value>*.

Constraint: if **range** = **Nag\_Indices**,  $1 \leq \mathbf{il} \leq \mathbf{iu} \leq \mathbf{n}$ .

### NE\_ENUM\_REAL\_2

On entry, **range** = *<value>*, **vl** = *<value>*, **vu** = *<value>*.

Constraint: if **range** = **Nag\_Interval**, **vl** < **vu**.

### NE\_CONVERGENCE

If **range** = **Nag\_AllValues** or **range** = **Nag\_Interval**, the algorithm failed to compute some (or all) of the required eigenvalues to the required accuracy. More precisely, **iblock**(*i*) < 0 indicates that the *i*th eigenvalue (stored in **w**(*i*)) failed to converge.

If **range** = **Nag\_Indices**, the algorithm failed to compute some (or all) of the required eigenvalues. Try calling the routine again with **range** = **Nag\_AllValues**.

If **range** = **Nag\_Indices**, the algorithm failed to compute some (or all) of the required eigenvalues. Try calling the routine again with **range** = **Nag\_AllValues**. If **range** = **Nag\_AllValues** or **range** = **Nag\_Interval**, the algorithm failed to compute some (or all) of the required eigenvalues to the required accuracy. More precisely, **iblock**(*i*) < 0 indicates that the *i*th eigenvalue (stored in **w**(*i*)) failed to converge.

No eigenvalues have been computed. The floating-point arithmetic on the computer is not behaving as expected.

### NE\_ALLOC\_FAIL

Memory allocation failed.

### NE\_BAD\_PARAM

On entry, parameter *<value>* had an illegal value.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

**7 Accuracy**

The eigenvalues of  $T$  are computed to high relative accuracy which means that if they vary widely in magnitude, then any small eigenvalues will be computed more accurately than, for example, with the standard  $QR$  method. However, the reduction to tridiagonal form (prior to calling the function) may exclude the possibility of obtaining high relative accuracy in the small eigenvalues of the original matrix if its eigenvalues vary widely in magnitude.

**8 Further Comments**

There is no complex analogue of this function.

**9 Example**

See Section 9 of the document for nag\_dormtr (f08fgc).

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